# Double Negative Metamaterial Sensor Based on Microring Resonator 

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#### Abstract

Metamaterials are artificial media structured on a size scale smaller than the wavelength of external stimuli, and may provide novel tools to significantly enhance the sensitivity and resolution of the sensors. In this paper, we derive the dispersion relation of cylindrical dielectric waveguide loaded on double negative metamaterial (DNM) layer, and compute the resonant frequencies and electric field distribution of the corresponding Whispering-Gallery-Modes (WGM). Theoretical results of resonant frequency and electric field distribution are in good agreement with the simulation results. We show that the DNM sensor based on microring resonator possesses higher sensitivity than the traditional microring sensor since the amplification of evanescent wave, and with the increase of metamaterial layer thickness, the sensitivity will be increased greatly. It might open an avenue for designing perfect sensors.


Index Terms-Evanescent wave, metamaterials, microring, sensor.

## I. Introduction

0F PARTICULAR interest, artificially engineered metamaterials are composed of electrically small inclusions that may tailor the material's effective permittivity and permeability with positive, near zero, or negative values. The peculiar properties and often counterintuitive behavior of metamaterials opens possibilities to form various structures with novel functionalities such as perfect lens, cloak, directive antenna, transparent devices, etc. [1]-[5]. Recently, great interest has been devoted to sensing applications of metamaterials. For example, Jakšić et al. [6] investigated some peculiarities of electromagnetic metamaterials convenient for plasmon-based chemical sensing with enhanced sensitivity, and they envisioned the practical applications of metamaterial-based sensors in biosensing, chemical sensing, environmental sensing, homeland security, etc. He et al. [7], studied the resonant modes of a 2 D subwavelength open resonator, and showed it was suitable

[^0]for biosensing. Cubukcu et al. [8] reported a surface enhanced molecular detection technique with zeptomole sensitivity that relies on the resonant electromagnetic coupling between a split ring resonator and the infrared vibrational modes of molecules. Melik et al. [9] demonstrated the implementation of metamaterials in wireless RF-MEMS strain sensors, and highly desirable properties were obtained. Alù et al. [10] proposed a method of dielectric sensing using $\varepsilon$ near-zero narrow waveguide channels. Shreiber [11] developed a novel microwave nondestructive evaluation sensor using metamaterial lens for detection of material defects small relative to a wavelength. Zheludev [12] analyzed the road ahead for metamaterials, and pointed out that sensor applications are another growth area in metamaterials research. Our team [13]-[15] studied the performance of metamaterial sensor, and show that the sensitivity and resolution of the sensors can be greatly enhanced by metamaterials.

WGM is a morphology-dependent resonance. It occurs when light within a dielectric microsphere resonator, which has a higher refractive index than its surrounding. After repeated total internal reflections at the curved boundary, the electromagnetic field can close on itself and give rise to resonances [16]. The WGM resonance phenomenon has attracted increasing attention due to their high potential for the realization of microcavity lasers [17], quantum computers [18], sensing applications [19]-[27], etc. Examples of the applications of WGM sensors include biosensing [22], nanoparticle detection [23], singlemolecule detection [24], temperature measurement [25], ammonia detection [26], and TNT detection [27]. However, to the best of our knowledge, there is no report about the DNM sensor based on microring resonator operating in WGM.

The purpose of this paper is to investigate the performance of the DNM sensor and to illustrate how it is different from the traditional microring resonator sensor. First, we derive the dispersion relation of the cylindrical dielectric waveguide loaded on DNM layer, and compute the resonant frequencies and electric field distributions of the corresponding WGMs. Then, we make full wave simulation on the performance of the DNM sensor, and compared with the theoretical results. Finally, we show that the DNM sensor possesses much higher sensitivity than traditional microring resonator sensor, and the mechanism behind these phenomena is verified by theoretical analysis and simulation.

## II. Theoretical Analysis

The geometry of cylindrical dielectric waveguide loaded with a layer of metamaterials is shown in Fig. 1. The inner side of the cylindrical dielectric waveguide $\left(\varepsilon_{3}, \mu_{3}\right)$ is loaded with a


Fig. 1. (Color online) (a) Schematic illustration of the cylindrical dielectric waveguide loaded with a metamaterial layer colored in red. (b) Cross section of the waveguide. $\mu_{1}=\mu_{3}=\mu_{4}=\mu_{0}, \varepsilon_{2}=-\varepsilon_{0}, \mu_{2}=-\mu_{0}$.
layer of metamaterials $\left(\varepsilon_{2}, \mu_{2}\right)$. Material parameters of the inner region and the outer region is denoted as $\varepsilon_{1}, \mu_{1}, \varepsilon_{4}$, and $\mu_{4}$. The axial fields in regions $1,2,3$, and 4 for TM mode [28] are

$$
\begin{align*}
& E_{z}^{(1)}(r, \theta)=A_{m} J_{m}\left(p_{1} r\right) e^{ \pm j m \theta}  \tag{1a}\\
& E_{z}^{(2)}(r, \theta)=\left(B_{m} J_{m}\left(p_{2} r\right)+B_{m}^{\prime} Y_{m}\left(p_{2} r\right)\right) e^{ \pm j m \theta}  \tag{1b}\\
& E_{z}^{(3)}(r, \theta)=\left(C_{m} J_{m}\left(p_{3} r\right)+C_{m}^{\prime} Y_{m}\left(p_{3} r\right)\right) e^{ \pm j m \theta}  \tag{1c}\\
& E_{z}^{(4)}(r, \theta)=D_{m} K_{m}(q r) e^{ \pm j m \theta} \tag{1d}
\end{align*}
$$

where $A_{m}, B_{m}, C_{m}, D_{m}, B_{m}^{\prime}$, and $C_{m}^{\prime}$ are chosen here to weight the field but they are interdependent. $J_{m}, Y_{m}$, and $K_{m}$ are, respectively, the Bessel functions of the first kind, of the second kind, and the modified Bessel function of the second kind. $p_{1}=\sqrt{\omega^{2} \varepsilon_{1} \mu_{1}-\beta^{2}}, p_{2}=\sqrt{\omega^{2} \varepsilon_{2} \mu_{2}-\beta^{2}}$, $p_{3}=\sqrt{\omega^{2} \varepsilon_{3} \mu_{3}-\beta^{2}}, q=\sqrt{\beta^{2}-\omega^{2} \varepsilon_{4} \mu_{4}} \cdot \beta$ is the propagation constant, and $m$ is the angular order. For an infinite cylindrical dielectric waveguide with negligible absorption and no axial component of the propagation constant $(\beta=0)$, TM mode degenerates to WGM [29], (1) becomes

$$
\begin{align*}
& E_{z}^{(1)}(r, \theta)=A_{m} J_{m}\left(p_{1} r\right) e^{ \pm j m \theta}  \tag{2a}\\
& E_{z}^{(2)}(r, \theta)=\left(B_{m} J_{m}\left(p_{2} r\right)+B_{m}^{\prime} Y_{m}\left(p_{2} r\right)\right) e^{ \pm j m \theta}  \tag{2b}\\
& E_{z}^{(3)}(r, \theta)=\left(C_{m} J_{m}\left(p_{3} r\right)+C_{m}^{\prime} Y_{m}\left(p_{3} r\right)\right) e^{ \pm j m \theta}  \tag{2c}\\
& E_{z}^{(4)}(r, \theta)=D_{m}^{\prime} H_{m}^{(1)}\left(p_{4} r\right) e^{ \pm j m \theta} \tag{2d}
\end{align*}
$$

where $p_{1}=\omega \sqrt{\varepsilon_{1} \mu_{1}}, p_{2}=\omega \sqrt{\varepsilon_{2} \mu_{2}}, p_{3}=\omega \sqrt{\varepsilon_{3} \mu_{3}}, p_{4}=$ $\sqrt{-q^{2}}=\omega \sqrt{\varepsilon_{4} \mu_{4}}, D_{m}^{\prime}=(i \pi / 2) e^{i m \pi / 2} D_{m}, H_{m}^{(1)}$ is the Hankel function of the first kind. The relation between $H_{m}^{(1)}$ and $K_{m}$ is $K_{m}(-i z)=(i \pi / 2) e^{i m \pi / 2} H_{m}^{(1)}(\mathrm{z})$. For TM mode in the cylindrical dielectric waveguide, transverse magnetic fields can be obtained as

$$
\begin{align*}
& H_{r}(r, \theta)=\frac{1}{p^{2}}\left(\frac{j \omega \varepsilon}{r} \frac{\partial E_{z}(r, \theta)}{\partial \theta}\right)  \tag{3a}\\
& H_{\theta}(r, \theta)=\frac{1}{p^{2}}\left(-j \omega \varepsilon \frac{\partial E_{z}(r, \theta)}{\partial r}\right) . \tag{3b}
\end{align*}
$$

The field matching equations at the boundary surface, $r=r_{1}$, $r=r_{2}$, and $r=r_{3}$ are expressed as

$$
\begin{aligned}
& E_{z}^{(1)}\left(r_{1}, \theta\right)=E_{z}^{(2)}\left(r_{1}, \theta\right), H_{\theta}^{(1)}\left(r_{1}, \theta\right)=H_{\theta}^{(2)}\left(r_{1}, \theta\right), \\
& E_{z}^{(2)}\left(r_{2}, \theta\right)=E_{z}^{(3)}\left(r_{2}, \theta\right), H_{\theta}^{(2)}\left(r_{2}, \theta\right)=H_{\theta}^{(3)}\left(r_{2}, \theta\right), \\
& E_{z}^{(3)}\left(r_{3}, \theta\right)=E_{z}^{(4)}\left(r_{3}, \theta\right), H_{\theta}^{(3)}\left(r_{4}, \theta\right)=H_{\theta}^{(4)}\left(r_{4}, \theta\right) .
\end{aligned}
$$


(a)

Fig. 2. (Color online) Simulation model. (a) Homogeneous sensing. (b) Surface sensing.

Satisfying these conditions gives

$$
\begin{equation*}
[M]\left[A_{m}, B_{m}, B_{m}^{\prime}, C_{m}, C_{m}^{\prime}, D_{m}^{\prime}\right]^{T}=0 \tag{4}
\end{equation*}
$$

where equations (5)-(10) are shown at the bottom of the next page.

The dispersion equation can be obtained by setting $|M|=0$. Coefficients $B_{m}, B_{m}^{\prime}, C_{m}, C_{m}^{\prime}$, and $D_{m}^{\prime}$ can be expressed in terms of the arbitrary coefficient $A_{m}$, which can be determined from the excitation condition, and $B_{m}=f_{m}^{(1)} A_{m}, B_{m}^{\prime}=$ $f_{m}^{(2)} A_{m}, C_{m}=f_{m}^{(3)} A_{m}, C_{m}^{\prime}=f_{m}^{(4)} A_{m}, D_{m}^{\prime}=f_{m}^{(5)} A_{m}$. The coefficients $f_{n}^{(1)}, f_{n}^{(2)}, f_{n}^{(3)}, f_{n}^{(4)}$, and $f_{n}^{(5)}$ may be found from (4).

## III. Results and Discussions

## A. Simulation Model

Simulation models of the DNM sensor are shown in Fig. 2. A layer of metamaterials with thickness $t$ is located in the inner side of the microring. Permittivity and permeability of the metamaterials are $\varepsilon_{2}=-\varepsilon_{0}, \mu_{2}=-\mu_{0}$. Width of the microring and the waveguide is $w=0.3 \mu \mathrm{~m}$. The outer diameter of the microring is $d=5 \mu \mathrm{~m}$. The distance from outer microring to the waveguide is $g=0.232 \mu \mathrm{~m}$. The permittivity of the microring and the waveguide is $\varepsilon_{3}=10.24 \varepsilon_{0}$. Fig. 2(a) is the simulation model for homogeneous sensing. The dielectric core with permittivity $\varepsilon_{1}=\varepsilon_{r} \varepsilon_{0}$ is colored in gray. Fig. $2(\mathrm{~b})$ is the simulation model for surface sensing. The dielectric substance with thickness $t_{s}$ and permittivity $\varepsilon_{1}=\varepsilon_{r} \varepsilon_{0}$ is attached to the metamaterial layer.

## B. Results and Discussions

Frequency spectrum of the DNM sensor for homogeneous sensing is simulated by the commercial software COMSOL multiphysics, as shown in Fig. 3. It is obtained by frequency sweep. The sinusoidal excitation with amplitude of $1 \mathrm{~V} / \mathrm{m}$ is set at port A of the waveguide. A probe is located at the point that possesses maximum electric filed at resonant state to record variation of $\left|E_{z}\right|$ with frequency. From left to right, the spectral lines represent mode $25,26,27,28$, and 29 of the DNM sensor. The inset shows the amplification in the frequency range of 198.68-198.72 THz. A comparison of the analytical and simulated resonant frequency for the microring resonator sensor and the DNM sensor is shown in Table I. It is seen that the


Fig. 3. Frequency spectrum of the DNM sensor. Thickness of the metamaterial layer is $t=0.12 \mu \mathrm{~m}$. Permittivity of the dielectric core is $\varepsilon_{r}=1$.
theoretical results are in good agreement with the simulation results.

TABLE I
Comparison of the Theoretical Resonant Frequency ( $f_{t} \mathrm{THz}$ ) and Simulated Resonant Frequency ( $f_{s}$ THz) for the Microring Resonator Sensor and the DNM Sensor

| Mode $(\mathrm{m})$ | 25 | 26 | 27 | 28 | 29 |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $f_{t}(\mathrm{t}=0)$ | 186.145 | 192.199 | 198.251 | 204.300 | 210.347 |
| $f_{s}(\mathrm{t}=0)$ | 186.156 | 192.208 | 198.257 | 204.304 | 210.351 |
| $f_{t}(\mathrm{t}=0.12 \mu \mathrm{~m})$ | 186.564 | 192.630 | 198.693 | 204.754 | 210.815 |
| $f_{s}(\mathrm{t}=0.12 \mu \mathrm{~m})$ | 186.577 | 192.640 | 198.701 | 204.761 | 210.821 |

Taking mode 27 as an example, electric field distribution of the microring sensor and the DNM senor is simulated and compared with that of the analytical results, as shown in Fig. 4. The theoretical electric field distribution is obtained by substituting (6)-(10) in to (2). The simulating results agree quite well with the analytical results. From Fig. 4(a) and (b), we can observe that the maximum electric field is distributed inside the ring for the microring resonator sensor without the metamaterial layer. For the DNM sensor, maximum electric field permeates into the surface of the metamaterial layer, as shown in

$$
\begin{align*}
& {[M]=\left[\begin{array}{cccccc}
J_{m}\left(p_{1} r_{1}\right) & -J_{m}\left(p_{2} r_{1}\right) & -Y_{m}\left(p_{2} r_{1}\right) & 0 & 0 & 0 \\
-\frac{\varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right)}{p_{1}} & \frac{\varepsilon_{2} J_{m}^{\prime}\left(p_{2} r_{1}\right)}{p_{2}} & \frac{\varepsilon_{2} Y_{m}^{\prime}\left(p_{2} r_{1}\right)}{p_{2}} & 0 & 0 & 0 \\
0 & J_{m}\left(p_{2} r_{2}\right) & Y_{m}\left(p_{2} r_{2}\right) & -J_{m}\left(p_{3} r_{2}\right) & -Y_{m}\left(p_{3} r_{2}\right) & 0 \\
0 & -\frac{\varepsilon_{2} J_{m}^{\prime}\left(p_{2} r_{2}\right)}{p_{2}} & -\frac{\varepsilon_{2} Y_{m}^{\prime}\left(p_{2} r_{2}\right)}{p_{2}} & \frac{\varepsilon_{3} J_{m}^{\prime}\left(p_{3} r_{2}\right)}{p_{3}} & \frac{\varepsilon_{3} Y_{m}^{\prime}\left(p_{3} r_{2}\right)}{p_{3}} & 0 \\
0 & 0 & 0 & J_{m}\left(p_{3} r_{3}\right) & Y_{m}\left(p_{3} r_{3}\right) & -H_{m}^{(1)}\left(p_{4} r_{3}\right) \\
0 & 0 & 0 & -\varepsilon_{3} J_{m}^{\prime}\left(p_{3} r_{3}\right) & -\frac{\varepsilon_{3} Y_{m}^{\prime}\left(p_{3} r_{3}\right)}{p_{3}} & \frac{\varepsilon_{4} H_{m}^{\prime \prime}\left(p_{4} r_{3}\right)}{p_{4}}
\end{array}\right]}  \tag{5}\\
& f_{m}^{(1)}=\frac{\frac{\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)}{\left(p_{1} \varepsilon_{2} J_{m}^{\prime}\left(p_{2} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{2} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)}}{f_{m}^{(2)}=\frac{-\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right)}{\left(p_{1} \varepsilon_{2} J_{m}^{\prime}\left(p_{2} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{2} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)}} \begin{aligned}
\left(p _ { 2 } \varepsilon _ { 3 } Y _ { m } ^ { \prime } ( p _ { 3 } r _ { 2 } ) \left(J_{m}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)\right)+Y_{m}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)\right.\right.\right.
\end{aligned}  \tag{6}\\
& \left.-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right)+p_{3} \varepsilon_{2} Y_{m}\left(p_{3} r_{2}\right)\left(J_{m}^{\prime}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) \cdot Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\right) \tag{7}
\end{align*}
$$

$\left(p_{2} \varepsilon_{3} J_{m}^{\prime}\left(p_{3} r_{2}\right)\left(J_{m}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)+Y_{m}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right.\right.\right.$

$$
\left.\left.-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)\right)\right)+p_{3} \varepsilon_{2} J_{m}\left(p_{3} r_{2}\right)\left(J_{m}^{\prime}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) \cdot Y_{m}^{\prime}\left(p_{2} r_{1}\right)-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)\right)\right.
$$

$$
\begin{equation*}
f_{m}^{(4)}=\frac{\left.\left.+Y_{m}^{\prime}\left(p_{2} r_{2}\right) \cdot\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\right)\right)}{\left(p_{1} p_{2} \varepsilon_{2} \varepsilon_{3}\left(J_{m}^{\prime}\left(p_{2} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-J_{m}\left(p_{2} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\left(J_{m}^{\prime}\left(p_{3} r_{2}\right) \cdot Y_{m}\left(p_{3} r_{2}\right)-J_{m}\left(p_{3} r_{2}\right) Y_{m}^{\prime}\left(p_{3} r_{2}\right)\right)\right)} \tag{9}
\end{equation*}
$$

$$
c_{1}\left(Y _ { m } ( p _ { 3 } r _ { 3 } ) \left(p _ { 2 } \varepsilon _ { 3 } J _ { m } ^ { \prime } ( p _ { 3 } r _ { 2 } ) \left(J_{m}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\right.\right.\right.
$$

$$
\left.+Y_{m}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)\right)\right)
$$

$$
+p_{3} \varepsilon_{2} J_{m}\left(p_{3} r_{2}\right)\left(J_{m}^{\prime}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)\right)\right.
$$

$$
\left.+Y_{m}^{\prime}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) \cdot J_{m}\left(p_{2} r_{1}\right)-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\right)
$$

$$
+J_{m}\left(p_{3} r_{3}\right)\left(p _ { 2 } \varepsilon _ { 3 } Y _ { m } ^ { \prime } ( p _ { 3 } r _ { 2 } ) \left(J _ { m } ( p _ { 2 } r _ { 2 } ) \left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right.\right.\right.
$$

$$
\left.-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)\right)+Y_{m}\left(p_{2} r_{2}\right)\left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)\right.
$$

$$
\left.\left.-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\right)+p_{3} \varepsilon_{2} Y_{m}\left(p_{3} r_{2}\right)\left(J _ { m } ^ { \prime } ( p _ { 2 } r _ { 2 } ) \left(p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)\right.\right.
$$

$$
\left.-p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) \cdot Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)+Y_{m}^{\prime}\left(p_{2} r_{2}\right)\left(p_{1} \varepsilon_{2} J_{m}\left(p_{1} r_{1}\right) J_{m}^{\prime}\left(p_{2} r_{1}\right)\right.
$$

$$
\begin{equation*}
f_{m}^{(5)}=\frac{\left.\left.\left.\left.-p_{2} \varepsilon_{1} J_{m}^{\prime}\left(p_{1} r_{1}\right) J_{m}\left(p_{2} r_{1}\right)\right)\right)\right)\right)}{\left(p_{1} p_{2} \varepsilon_{2} \varepsilon_{3} H_{m}^{(1)}\left(p_{4} r_{3}\right)\left(J_{m}^{\prime}\left(p_{2} r_{1}\right) Y_{m}\left(p_{2} r_{1}\right)-J_{m}\left(p_{2} r_{1}\right) \cdot Y_{m}^{\prime}\left(p_{2} r_{1}\right)\right)\left(J_{m}^{\prime}\left(p_{3} r_{2}\right) Y_{m}\left(p_{3} r_{2}\right)-J_{m}\left(p_{3} r_{2}\right) Y_{m}^{\prime}\left(p_{3} r_{2}\right)\right)\right)} . \tag{10}
\end{equation*}
$$



Fig. 4. (Color online) Electric field distribution of the microring sensor operating at mode 27. (a) Theoretical result of the microring resonator sensor. (b) Simulating result of the microring resonator sensor. (c) Theoretical result of the DNM sensor. (d) Simulation result of the DNM sensor. Thickness of the metamaterial layer is $t=0.12 \mu \mathrm{~m}$.

Fig. 4(c) and (d). Therefore, this area will be quite sensitive in dielectric environment.

Fig. 5 shows the simulating results for homogeneous sensing. Permittivity $\left(\varepsilon_{r}\right)$ of the dielectric core varies form 1 to 1.1 with an interval of 0.02 . The spectra are red shifted with the increase of $\left(\varepsilon_{r}\right)$. From Fig. 5(a) and (b), we can obtain that the average frequency shift for the microring resonator sensor is about 7.562 GHz ; for the DNM sensor, the average frequency shift is about 116.137 GHz . Therefore, sensitivity of the DNM sensor is 15.358 times that of the traditional microring resonator sensor for homogeneous sensing.

Resonant frequency in Fig. 5 is calculated and compared with the theoretical method, as shown in Fig. 6. Blue and green lines denote the results for the DNM sensor, obtained by theoretical method and numerical simulation, respectively. Red and cyan lines denote the results for the microring resonator sensor. From Fig. 6, we can observe that the simulation results agree well with the theoretical results. With an increase of 0.02 in core medium permittivity, the average frequency shift of the microring sensor is quite small. When a layer of metamaterials is attached to the inner side of the microring resonator, the average frequency shift of the DNM sensor will be greatly increased. As a consequence, the DNM sensor possesses much higher sensitivity than the traditional microring resonator sensor.

To reveal the mechanism behind these phenomena, we plot the electric field distribution along $x$ axis from -3 to $-1.5 \mu \mathrm{~m}$ for mode 27, as shown in Fig. 7. Permittivity of the core medium is set to be $\varepsilon_{r}=1$. It is seen that the electric field intensity increases with metamaterial layer thickness $(t)$. The inset shows the electric filed distribution of the DNM sensor. From Fig. 7, we can clearly observe that the stronger electric field of evanes-


Fig. 5. (Color online) Resonant frequency spectrum of mode 27 with respect to the change of core medium permittivity $\varepsilon_{r}$. From left to right, the curves correspond to $\varepsilon_{r}=1,1.02,1.04,1.06,1.08$, and 1.1 , respectively. (a) The microring resonator sensor. (b) The DNM sensor. Thickness of the metamaterial layer is $t=0.12 \mu \mathrm{~m}$.


Fig. 6. (Color online) Relation between $\varepsilon_{r}$ and resonant frequency.
cent wave penetrates into the detecting region when the thickness of metamaterial layer increases. Therefore, the essence for the enhancement of sensitivity is the evanescent wave amplified by metamaterials.

Fig. 8 shows the relation between core medium permittivity and resonant frequency for different metamaterial layer thickness. Permittivity of the core medium increases from 1 to 1.1


Fig. 7. (Color online) Electric field distribution along $x$ axis from -3 to $-1.5 \mu \mathrm{~m}$ for the DNM sensor operating in mode 27 . The inset shows the electric field distribution of the DNM sensor, of which the metamaterial layer thickness is $t=0.12 \mu \mathrm{~m}$.


Fig. 8. (Color online) Homogeneous sensing. Relation between $\varepsilon_{r}$ and resonant frequency for a variation of metamaterial layer thickness.
with an interval of 0.02 . Resonant frequency shift varies linearly with the permittivity of substance. For the microring resonator sensor, average frequency shift with response to an increase of 0.02 in core medium permittivity is only 7.562 GHz . For the DNM sensor, average frequency shift increases with metamaterial layer thickness. When the thickness of the metamaterial layer is increased to $0.06,0.09,0.12,0.15$, and $0.18 \mu \mathrm{~m}$, the corresponding average frequency shift will be $29.001,57.744$, $116.137,235.972$, and 483.071 GHz , respectively.

Surface sensing of the DNM sensor can also be analyzed according to the above procedures, and it is not shown here for brevity. Fig. 9 portrays the simulation results of surface sensing. Thickness of the adsorbed substance is $0.075 \mu \mathrm{~m}$. Similarly, average frequency shift increases with metamaterial thickness. When metamaterial layer thickness increases from 0.06 to 0.18 $\mu \mathrm{m}$ with an interval of $0.03 \mu \mathrm{~m}$, the average frequency shift of the DNM sensor with response to an increase of 0.02 in surface medium permittivity is about $24.525,49.454,99.984$, 204.167, and 419.610 GHz , respectively. Therefore, sensitivity


Fig. 9. (Color online) Surface sensing. Relation between $\varepsilon_{r}$ and resonant frequency for a variation of metamaterial layer thickness.
of the DNM sensor can be greatly improved by increasing the thickness of the metamaterial layer attached to its inner side.

## IV. CONCLUSION

WGMs of dielectric waveguide with a layer of metamaterials is theoretically analyzed, and the dispersion relation is derived. Analytical results of the resonant frequency shift and electric field distribution of the sensor is in good agreement with the simulation results. We show that the DNM sensor possesses a higher sensitivity than the traditional microring resonator sensor, since the amplification of evanescent wave. Moreover, the sensitivity will be further improved by increasing the thickness of the metamaterial layer. It opens an avenue for design novel sensors with specified sensitivity.

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