On the distillation of Gaussian states with Gaussian operations

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We will show that no distillation protocol for Gaussian quantum states exists that relies on (i) arbitrary local unitary operations that preserve the Gaussian character of the state and (ii) homodyne detection together with classical communication and postprocessing by means of local Gaussian unitary operations on two symmetric identically prepared copies. This analysis shows that unlike the finite-dimensional case, where entanglement can be distilled in an iterative protocol using two copies at a time, there is no such procedure in the case of continuous variables for Gaussian initial states and the above Gaussian operations. The ramifications for the distribution of Gaussian states over large distances will be outlined. We will also comment on the generality of the approach and sketch the most general form of a Gaussian local operation with classical communication in a bi-partite setting.

In most practical implementations of information processing devices sophisticated methods are necessary in order to preserve the coherence of the involved quantum states. Even the mere preparation of an entangled state of spatially distributed quantum systems requires such techniques: once prepared locally and then distributed, an entangled state will to some extent deteriorate from a highly entangled state to a less correlated state through the process of decoherence. This process can quite obviously not be entirely avoided. However, one may prepare and distribute several identical entangled states, and then apply appropriate partly measuring local quantum operations to obtain states that are similar to the highly entangled original state. This is only possible at the expense that one has fewer identically prepared systems or copies at hand, but this is a small price to pay. Appropriately indeed, this process has been given the name distillation [1], as fewer more highly entangled states are 'distilled' from a supply of many less entangled states. It was one of the major successes of the field of quantum information science to realize that for two-level systems such a distillation procedure may be performed on only two copies at a time, and it requires only two steps: (i) a local unitary operation, and (ii) a local measurement, together with the classical communication about the measurement outcome. Based on the measurement outcome further local unitary operations are then implemented.

Such distillation protocols may also be of crucial importance in the infinite-dimensional setting. Quantum information science over continuous variables has seen an enormous progress recently, both in theory and experiment, mostly involving Gaussian states of field modes in a quantum optical setting [2,3]. Quite naturally, one should expect that a similar distillation procedure also works for Gaussian states in the infinite-dimensional case, also under the preservation of the Gaussian character of the state. If one transmits two pure twomode squeezed Gaussian states through lossy optical systems such as fibers, the corresponding modes being from now on labeled A1, A2, B1, and B2, one obtains two identical copies of less entangled symmetric states [4]. A feasible distillation protocol preserving the Gaussian character may consist of the subsequent steps (see Fig. 1): (i) Application of any local unitary operation that preserves the Gaussian character of the state. That is, one may implement any unitary operations U_A and U_B on both A1 and A2 on one hand and B1 and B2 on the other hand corresponding to symplectic transformations $S_A, S_B \in Sp(4, \mathbb{R})$ [5]. This set includes all two-mode and one-mode squeezings, mixing at beam splitters and phase shifts. To specify these operations 20 real parameters are necessary. Note that we do not require both parties to realize the same transformation [6].

(ii) A homodyne measurement on the modes A2 and B2. The parties communicate classically about the outcome of the measurement, and may postprocess the states of modes A1 and B1 with unitary Gaussian operations.



FIG. 1. The class of considered feasible distillation protocols.

The main result of this Letter is that very much as a surprise, none of these protocols amounts to a distillation protocol. No matter how ingeniusely the local unitary operation is chosen the degree of entanglement can not be increased. The optimal procedure is simply to do nothing at all, which means that at least no entanglement is lost. The degree of entanglement will be measured in terms of the log-negativity, which is defined as $E_N(\rho) = \log_2 \|\rho^{T_A}\|$ for a state ρ , where $\|.\|$ denotes the trace norm, and ρ^{T_A} is the partial transpose of ρ . The lognegativity has been shown to be an entanglement measure in the sense that it is non-increasing on average under local operations with classical communication [7], and is to date the only known feasible measure of entanglement for Gaussian states. For pure (and for symmetric mixed) Gaussian states it is identical to the degree of squeezing. This means that as a corollary of the main result, it follows that with Gaussian operations as specified above one cannot transform two identically prepared two-mode squeezed vacua into a single twomode squeezed vacuum state with a higher degree of squeezing.

We will start by fixing the notation. Gaussian states [8] of an *n*-mode system are completely characterized by their first and second moments. The first moments are the expectation values of the canonical coordinates. The second moments can be collected in the real symmetric covariance matrix [9] $\Gamma \in C(2n) \subset M(2n, \mathbb{R})$, where $M(2n, \mathbb{R})$ denotes the set of real $2n \times 2n$ -matrices, and C(2n) the subset of matrices obeying the Heisenberg uncertainty principle [9]. The linear transformations from one set of canonical coordinates to another which preserve the canonical commutation relations form the group of real linear symplectic transformations $Sp(2n, \mathbb{R})$ [5]. A symplectic transformation S changes the covariance matrix according to $\Gamma \longmapsto S\Gamma S^T$, while states undergo a unitary operation $\rho \longmapsto U(S)\rho U(S)^{\dagger}$. The n = 4 modes A1, A2, B1, B2 will be equipped with the canonical operators $(X_{A1}, P_{A1}, \dots, X_{B2}, P_{B2})$. To make the notation more transparent, both tensor products and direct sums will carry a label indicating the underlying split, meaning either A, B or 1, 2. We state the main result of this Letter in form of a theorem:

Theorem. – Let $\rho \otimes \rho$ be two identically prepared symmetric Gaussian states of two-mode systems consisting of the parts A1, A2, B1, and B2, respectively, each of which having the covariance matrix

$$\Gamma^{(0)} = \begin{pmatrix} a & 0 & c & 0\\ 0 & a & 0 & -c\\ c & 0 & a & 0\\ 0 & -c & 0 & a \end{pmatrix}, \ a \ge 1, \ 0 \le c \le (a^2 - 1)^{1/2},$$
(1)

let $S_A, S_B \in Sp(4, \mathbb{R})$ be any symplectic transformations with U_A and U_B being the respective associated unitaries, and let

$$\rho' = (U_A \otimes_{A,B} U_B)(\rho \otimes_{1,2} \rho)(U_A \otimes_{A,B} U_B)^{\dagger}.$$

Then any state ρ'' that is obtained from ρ' via a selective homodyne measurement on systems A2 and B2 satisfies $E_N(\rho'') \leq E_N(\rho)$, that is, the degree of entanglement can only decrease.

The proof of this statement will turn out to be quite technically involved, and while the statement itself is concerned with practical quantum optics, the techniques used in the proof will be mostly taken from matrix analysis [10]. In order to give the general argument more structure, the proof is split into several lemmata. The entire proof will be formulated in terms of covariance matrices, rather than in terms of the states themselves. Essentially, the complexity of the argument is due to the fact that the homodyne measurement is reflected as a complicated non-linear map on the level of covariance matrices.

The log-negativity of a state σ of a two-mode system can be easily expressed in terms of the entries of the associated covariance matrix $\gamma \in C(4)$. The latter can be partitioned in block form according to

$$\gamma = \begin{pmatrix} \gamma_A & \gamma_C \\ \gamma_C^T & \gamma_B \end{pmatrix}, \ \gamma_A, \gamma_B, \gamma_C \in M(2, R).$$
(2)

The log-negativity $E_N(\sigma)$ is then given by [7]

$$E_N(\sigma) = \begin{cases} -(\log \circ f)(\gamma), & \text{if } f(\gamma) < 1, \\ 0 & \text{otherwise.} \end{cases}$$
(3)

where the function $f: C(4) \longrightarrow \mathbb{R}^+$ is defined as

$$f(\gamma) = \left((\det[\gamma_A] + \det[\gamma_B])/2 - \det[\Gamma_C] \right) - \left[\left((\det[\gamma_A] + \det[\gamma_B])/2 - \det[\gamma_C] \right)^2 - \det[\gamma] \right]^{1/2}.$$
(4)

The covariance matrix associated with the Gaussian state ρ' in the Theorem will be denoted as $\Gamma' \in C(8)$. For any $S_A, S_B \in Sp(4, \mathbb{R})$ this covariance matrix of the modes A1, A2, B1, and B2 becomes

$$\Gamma' := (S_A \oplus_{A,B} S_B) (\Gamma^{(0)} \oplus_{1,2} \Gamma^{(0)}) (S_A \oplus_{A,B} S_B)^T$$
(5)

The first step is to relate the covariance matrix Γ'' associated with the state after the measurement to a Schur complement [10]. This Schur complement structure is a general feature of general Gaussian operations and will be further discussed at the end of the letter.

Lemma 1. $-Let \Gamma' \in C(8)$ be a covariance matrix of systems A1, A2, B1, and B2 associated with a state ρ' , which can be written in block form as

$$\Gamma' = \begin{pmatrix} C_1 & C_3 \\ C_3^T & C_2 \end{pmatrix},\tag{6}$$

where $C_1, C_2, C_3 \in M(4, \mathbb{R})$. The covariance matrix of the state that is obtained by a projection in A2 and B2 on the pure Gaussian state with covariance matrix $D_d :=$ $diag(1/d, d, 1/d, d) \in C(4), d > 0$, is then given by

$$\Gamma'' = C_1 - C_3 (C_2 + D_d^2)^{-1} C_3^T.$$
(7)

Proof. This statement can be most conveniently be shown in terms of the characteristic function χ [8]. By employing the Weyl (displacement) operator, the state ρ' associated with the covariance matrix Γ' can be written in terms of the characteristic function according to $\rho' = (1/\pi^4) \int d^8 \xi W(-\xi) \chi(\xi)$ (see, e.g., Ref. [11]). The projection corresponds on the level of the characteristic function therefore to an incomplete Gaussian integration. The characteristic function associated with the modes A1 and B1 can then be written as

$$\chi(\xi_1, \dots, \xi_4) = \int \frac{d\xi_5 \dots d\xi_8}{\pi^2} e^{-\xi^T \Gamma' \xi/2} e^{-\frac{1}{2d^2} (\xi_5^2 + \xi_7^2) - \frac{d^2}{2} (\xi_6^2 + \xi_8^2)}$$
$$= |C_2 + D_d^2|^{-1/2} e^{-(\xi_1, \dots, \xi_4) \Gamma''(\xi_1, \dots, \xi_4)^T/2}, \quad (8)$$

with Γ'' defined as in Eq. (7).

Hence, the resulting covariance matrix is given by the Schur complement $C_1 - C_3(C_2 + D_d^2)^{-1}C_3^T$ of the matrix

$$\begin{pmatrix} C_1 & C_3 \\ C_3^T & C_2 + D_d^2 \end{pmatrix}$$
(9)

with respect to the leading principal submatrix C_1 . The additional matrix D_d^2 originates from the projection in the modes A2 and B2. Note that although this Lemma has been formulated in terms of the projection on a certain class of pure Gaussian states, it applies to the projection on any pure Gaussian state in the modes A2 and B2: the projection on any other pure Gaussian state can be realized by an appropriate choice of the symplectic transformations S_A and S_B . Ideal homodyne detections can now be formulated as projections on 'infinitely squeezed' pure Gaussian states. The central feature is that the initial first moments do not affect the form of the covariance matrix after the measurement. Lemma 2 gives the form of the resulting covariance matrix in case of a homodyne detection in modes A2 and B2. In the limit $d \rightarrow 0$ the matrix D_d gives rise to a projection operator, and the inverse becomes a Moore Penrose inverse (MP) [10]:

Lemma 2. – In the notation of Lemma 1, the covariance matrix of modes A1 and B1 after a selective homodyne measurement in modes A2 and B2 is given by

$$M := \lim_{d \to 0} \Gamma_d = C_1 - C_3 (\pi C_2 \pi)^{MP} C_3^T, \qquad (10)$$

where $\pi = diag(1, 0, 1, 0)$.

Equipped with these preparatory considerations concerning the transformation of covariance matrices, we will now turn to the core of the proof. In order to be able to evaluate the logarithmic negativity according to Eq. (3), one needs to know the values of the invariants under local symplectic transformations, i.e., the determinants of four submatrices. To find an expression for all these determinants is however a quite difficult task. Instead, we will later make use of an upper bound of the logarithmic negativity that only involves determinants of principal submatrices [10] of Γ'' .

Lemma 3. – Let $M \in C(4)$ be defined as in Lemma 2. Then, independent of $S_A, S_B \in Sp(4, \mathbb{R})$,

$$det[M] = det[\Gamma^{(0)}] = (a^2 - c^2)^2.$$
(11)

Proof. According to Lemma 2, M is given by $M = \lim_{d\to 0} \Gamma_d$. The Schur complement of the matrix

$$\Gamma'_d := \begin{pmatrix} C_1 & C_3 \\ C_3^T & C_2 + D_d^2 \end{pmatrix}$$
(12)

is related to Γ'_d and one of its principal submatrices via the similarity transformation

$$\begin{pmatrix} \mathbf{1}_4 & X \\ 0 & \mathbf{1}_4 \end{pmatrix} \Gamma'_d \begin{pmatrix} \mathbf{1}_4 & 0 \\ X^T & \mathbf{1}_4 \end{pmatrix} = \begin{pmatrix} \Gamma_d & 0 \\ 0 & C_2 + D_d^2 \end{pmatrix},$$

where $X := -C_3(C_2 + D_d^2)^{-1}$. Hence, according to the determinant multiplication theorem we obtain det $[\Gamma'_d] = det[\Gamma_d] det[C_2 + D_d^2]$, which yields in the limit $d \to 0$

$$\det[M] = \det[P\Gamma'_d P + (\mathbf{1}_8 - P)]/\det[Q\Gamma'_d Q + (\mathbf{1}_8 - Q)],$$

where the projections P and Q are defined as P := diag(1, 1, 1, 1, 0, 1, 0, 1) and Q := diag(0, 0, 0, 0, 0, 1, 0, 1). With these tools, it is feasible to directly prove the statement of Lemma 3 by parameterizing $S_A, S_B \in Sp(4, \mathbb{R})$. Every $S \in Sp(4, \mathbb{R})$ can be written as a product S = VDW, where $V, W \in Sp(4, \mathbb{R}) \cap SO(4)$, and $D := \text{diag}(d_1, 1/d_1, d_2, 1/d_2)$ with $d_1, d_2 \in \mathbb{R}$.

Lemma 4. – Let $M \in C(4)$ be defined as in Lemma 2, and let M_A and M_B be the principal submatrices belonging to mode A1 and B1. Then, for all $S_A, S_B \in Sp(4, \mathbb{R})$,

$$det[M_A] \le det[\Gamma_A^{(0)}] = a^2, \ det[M_B] \le det[\Gamma_B^{(0)}] = a^2.$$
 (13)

Proof. M is defined as the covariance matrix corresponding to modes *A*1 and *B*1 after the projective measurements in both *A*2 and *B*2. Let us assume that one first performs the projective measurement in *A*2, leading to a the covariance matrix $N_A \in C(2)$ of the reduced state of *A*1. The covariance matrix M_A after the projection in *B*2 is then obtained as a Schur complement. In particular, M_A can be written as $M_A = N_A - P$, where $P \in M(2, \mathbb{R})$ is a real symmetric positive matrix. Hence, as M_A and N_A are also positive, det[M_A] ≤ det[N_A] [10]. In other words, one obtains an upper bound for det[M_A] when considering only a projective measurement in *A*1. The statement of Lemma 4 follows from Lemma 3 in the special case that c = 0: one can after a few steps conclude that then det[N_A] = a^2 , independent of $S_A, S_B \in Sp(4, \mathbb{R})$. The same reasoning applies to M_B .

The most important step is now an appropriate upper bound of the log-negativity of the resulting state. The actual bound might appear somewhat arbitrary, but it will turn out that it is exactly the tool that we need in the last step of the proof.

Lemma 5. – Let $\gamma \in C(4)$, partitioned as in Eq. (2). Then

$$f(\gamma) \ge g(\gamma) := \left[\left((det[\gamma_A] + det[\gamma_B])/2 \right)^{1/2} (14) - \left((det[\gamma_A] + det[\gamma_B])/2 - det[\gamma]^{1/2} \right)^{1/2} \right]^2.$$

Proof. $g(\gamma)$ can be expressed in terms of f as $g(\gamma) = f(\gamma')$,

$$\gamma' = \begin{pmatrix} \gamma'_A & \gamma'_C \\ \gamma'_C ^T & \gamma_B \end{pmatrix}, \quad \gamma'_A = \gamma'_B = a' \mathbf{1}_2, \quad \gamma'_C = \begin{pmatrix} c' & 0 \\ 0 & -c' \end{pmatrix},$$

where $a' := ((\det[\gamma_A]^2 + \det[\gamma_B]^2)/2)^{1/2}$ and $c' := (a'^2 - \det[\gamma]^{1/2})^{1/2}$. Hence, one has to prove that $f(\gamma') \leq f(\gamma)$. Firstly, note that $\det[\gamma] = \det[\gamma']$. Secondly, $(\det[\gamma_A] + \det[\gamma_B])/2 = a'^2$. Therefore, it remains to be shown that $c'^2 \geq |\det[\gamma_C]|$. This inequality is equivalent with

$$\left[(\det[\gamma_A] + \det[\gamma_B])/2 - |\det[\gamma_C]| \right]^2 - \det[\gamma] \ge 0, \quad (15)$$

which is a valid inequality, as $\gamma \in C(4)$.

We are now in the position to prove the validity of the Theorem. As most of the work has already been done in the lemmata, we only have to put the pieces together.

Proof of the Theorem. Let $M \in C(4)$ be the matrix defined as in Lemma 2. The log-negativity of the corresponding state of modes A1 and B1 is given by $-(\log \circ f)(M)$, if the final state is entangled at all, as we will assume from now on. Lemma 5 yields the bound $f(M) \geq g(M)$. In g(M), however, only the determinants of the principal submatrices are needed, bounds of which are available by virtue of Lemma 3 and 4. The function $h : [y, \infty) \to \mathbb{R}^+$ with $h(x) = (x^{1/2} - (x - y)^{1/2})^2$, y > 0, is a strictly monotone decreasing function of x. Therefore, using Lemma 3 and 4 one can conclude that $g(M) \geq g(\Gamma^{(0)})$. Moreover, $g(\Gamma^{(0)}) = f(\Gamma^{(0)})$, due to the special form of $\Gamma^{(0)}$, as can be easily verified. Hence,

$$f(M) \ge g(\Gamma^{(0)}) = f(\Gamma^{(0)}),$$
 (16)

which leads to $-(\log \circ f)(M) \leq -(\log \circ f)(\Gamma^{(0)})$. This is finally the desired result: it means that the degree of entanglement can only decrease.

We will finally comment on the generality of the approach. A general Gaussian operation is a quantum operation that maps all Gaussian states on Gaussian states [3]. Any general Gaussian local operation with classical communication (LOCCG) - trace-preserving or non-trace-preserving - can be decomposed into the subsequent steps: (i) Appending additional modes that have been prepared in a bi-partite separable Gaussian state. (ii) Application of any local unitary Gaussian operation on both the original and the additional system. These comprise operations corresponding to symplectic transformations and displacements in phase space. (iii) Projections on pure Gaussian states or ideal homodyne detections, which give rise to Schur complements on the level of covariance matrices as described above, together with the classical communication about the outcome (real numbers in case of homodyne detection, bits in case of dichotomic measurements including the projection on a pure Gaussian state in one outcome), and (iv) a partial trace, which corresponds to considering certain principal submatrices only. The proof is therefore restrictive in the sense that only two copies at a time are considered, other projections on Gaussian states are excluded, and no additional modes in separable states are allowed for. On intuitive grounds, however, one would hardly expect that separable resources qualify as having the ability to increase the degree of entanglement. The statement of the present paper proves that iterative protocols in strict analogy to the corresponding methods in finite dimensional settings certainly do not work. Indeed, the findings strongly suggest that Gaussian states cannot be distilled at all with Gaussian operations. Then (less feasible) non-linear physical effects [12] would have to be made use of in order to distill from a supply of Gaussian two-mode states [13]. Such techniques would then also be necessary for the realistic implementation of quantum repeaters [14] for continuous-variable systems when it comes to

the distribution of highly entangled Gaussian states over large distances.

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- [9] In terms of the 2n canonical coordinates (O₁,..., O_{2n}) := (X₁, P₁,..., X_n, P_n) the entries of the covariance matrix are given by Γ_{jk} = 2tr [ρ (O_j ⟨O_j⟩_ρ) (O_k ⟨O_k⟩_ρ)] iΣ_{jk}, j, k = 1,..., 2n, where the skew-symmetric 2n × 2n-matrix Σ is defined as [O_j, O_k] = iΣ_{jk}. Any symmetric matrix Γ ∈ M(2n, ℝ) satisfying the Heisenberg uncertainty principle Γ ≥ iΣ is a covariance matrix.
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